

Lista 8 - Indução Eletromagnética

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1. (a) da esquerda para a direita.

(b) da direita para a esquerda.

(c) da direita para a esquerda.

(d) da esquerda para a direita.

2. (a) $\Phi_B = \pi a^2 B_0 e^{-t/\tau}$.

(b) $\frac{d\Phi_B}{dt} = -\frac{\pi a^2 B_0}{\tau} e^{-t/\tau}$.

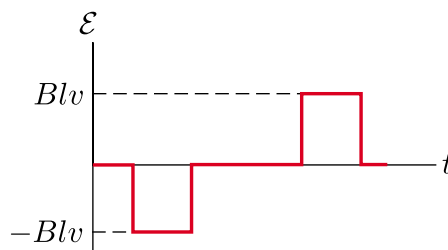
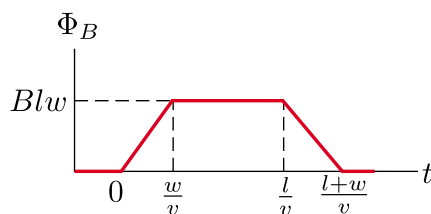
(c) $\mathcal{E} = \frac{\pi a^2 B_0}{\tau} e^{-t/\tau}$.

(d) $I = \frac{\pi a^2 B_0}{\tau R} e^{-t/\tau}$ e sentido anti-horário.

3. (a) $\Phi_B = \begin{cases} Bhvt & t \leq w/v \\ Bhv & w/v < t \leq l/v \\ Bh(l+w-vt) & l/v < t \leq (l+w)/v \\ 0 & t > (l+w)/v \end{cases}$

(b) $\mathcal{E} = \begin{cases} Bhv & t \leq w/v \\ 0 & w/v < t \leq l/v \\ -Bhv & l/v < t \leq (l+w)/v \\ 0 & t > (l+w)/v \end{cases}$

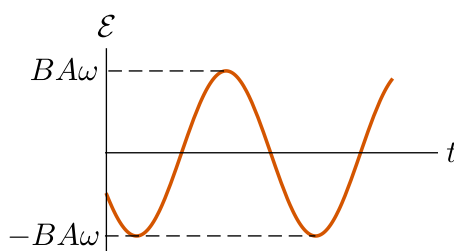
(c)



4. (a) $\Phi_B = BA \cos(\omega t - \theta_0)$.

(b) $\mathcal{E} = BA\omega \sin(\omega t - \theta_0)$.

(c)



(a) $\mathcal{E} = Blv$.

(b) $I = \frac{Blv}{R}$ com sentido $\hat{x}$.

(c) $\vec{F}_B = \frac{B^2 l^2 v}{R} \hat{y}$.

(d) $\vec{v}_{\text{term}} = -\frac{mgR}{B^2 l^2} \hat{y}$.

- (e) $\text{Pot}_{\text{grav}} = -\text{Pot}_{\text{diss}} = \frac{(mg)^2 R}{B^2 l^2}.$
6. (a) $\Phi_B = -\frac{\mu_0 I_0 \sin \omega t}{2\pi} b \ln \left(\frac{s+a}{s} \right).$
- (b) $\mathcal{M} = \frac{\mu_0}{2\pi} b \ln \left(\frac{s+a}{s} \right).$
- (c) $\mathcal{E} = \omega \frac{\mu_0 I_0 \cos \omega t}{2\pi} b \ln \left(\frac{s+a}{s} \right).$
7. (a) $\mathcal{L} = \mu_0 \frac{N^2 A}{L}.$
- (b) $\mathcal{E} = \mu_0 \frac{N^2 A}{L} \omega I_0 \sin \omega t.$
- (c) $\vec{E} = \frac{\mu_0}{2\sqrt{\pi}} \frac{N^2 \sqrt{A}}{L} \omega I_0 \sin \omega t \hat{\phi}.$
- (d) $u_B = \frac{\mu_0}{2} \frac{N^2}{L^2} I_0^2 \cos^2 \omega t.$